

The Matrix Logarithm: from Theory to Computation

Nick Higham
School of Mathematics
The University of Manchester

higham@ma.man.ac.uk
<http://www.ma.man.ac.uk/~higham/>

6th European Congress of Mathematics, July 2012

Matrix Logarithm

Definition

A logarithm of $A \in \mathbb{C}^{n \times n}$ is any matrix X such that $e^X = A$.

- Implicit definition.
- Properties, classification?

Outline

- 1 Definition and Properties
- 2 Applications
- 3 Theory
- 4 Computing the Matrix Logarithm and its Fréchet derivative

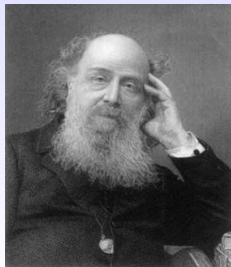
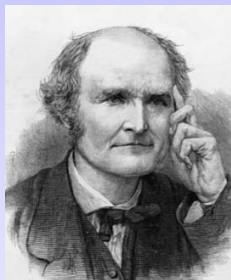
Cayley and Sylvester

Matrix algebra developed by **Arthur Cayley**, FRS (1821–1895) in *Memoir on the Theory of Matrices (1858)*.

- Cayley considered matrix square roots.

Term “**matrix**” coined in 1850 by **James Joseph Sylvester**, FRS (1814–1897).

- Gave (1883) first definition of $f(A)$ for general f .



Multiplicity of Definitions

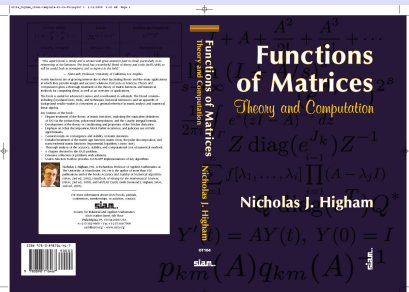
There have been proposed in the literature since 1880
eight distinct definitions of a matrix function,
by Weyr, Sylvester and Buchheim,
Giorgi, Cartan, Fantappiè, Cipolla,
Schwerdtfeger and Richter.

— **R. F. Rinehart,**
The Equivalence of Definitions
of a Matrix Function (1955)

Multiplicity of Definitions

There have been proposed in the literature since 1880 **eight distinct definitions** of a matrix function, by Weyr, Sylvester and Buchheim, Giorgi, Cartan, Fantappiè, Cipolla, Schwerdtfeger and Richter.

— **R. F. Rinehart, *The Equivalence of Definitions of a Matrix Function (1955)***



Jordan Canonical Form

$$Z^{-1}AZ = J = \text{diag}(J_1, \dots, J_p), \quad \underbrace{J_k}_{m_k \times m_k} = \begin{bmatrix} \lambda_k & 1 & & \\ & \lambda_k & \ddots & \\ & & \ddots & 1 \\ & & & \lambda_k \end{bmatrix}$$

Definition

$$f(A) = Zf(J)Z^{-1} = Z\text{diag}(f(J_k))Z^{-1},$$

$$f(J_k) = \begin{bmatrix} f(\lambda_k) & f'(\lambda_k) & \dots & \frac{f^{(m_k-1)}(\lambda_k)}{(m_k-1)!} \\ & f(\lambda_k) & \ddots & \vdots \\ & & \ddots & f'(\lambda_k) \\ & & & f(\lambda_k) \end{bmatrix}.$$

Primary and Nonprimary Logarithms

$$A = \text{diag}(1, 1, e, e).$$

Primary: $\log(A) = \text{diag}(0, 0, 1, 1).$

Nonprimary: $\log(A) = \text{diag}(0, 2\pi i, 1, 1).$

Cauchy Integral Theorem

Definition

$$f(A) = \frac{1}{2\pi i} \int_{\Gamma} f(z)(zI - A)^{-1} dz,$$

where f is analytic on and inside a closed contour Γ that encloses $\lambda(A)$.

Mercator's Series

By integrating $(1 + t)^{-1} = 1 - t + t^2 - t^3 + \dots$ between 0 and x we obtain Mercator's series (1668),

$$\log(1 + x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \dots, \quad |x| < 1.$$

For $A \in \mathbb{C}^{n \times n}$,

$$\log(I + A) = A - \frac{A^2}{2} + \frac{A^3}{3} - \frac{A^4}{4} + \dots, \quad \rho(A) < 1.$$

Composite Functions

Theorem

$$f(t) = g(h(t)) \Rightarrow f(A) = g(h(A)).$$

Corollary

$\exp(\log(A)) = A$ when $\log(A)$ is defined.

Composite Functions

Theorem

$$f(t) = g(h(t)) \Rightarrow f(A) = g(h(A)).$$

Corollary

$$\exp(\log(A)) = A \text{ when } \log(A) \text{ is defined.}$$

What about $\log(\exp(A)) = A$?

Matrix unwinding number

$$\mathcal{U}(A) = \frac{A - \log(\exp(A))}{2\pi i}.$$

Outline

- 1 Definition and Properties
- 2 Applications**
- 3 Theory
- 4 Computing the Matrix Logarithm and its Fréchet derivative

Toolbox of Matrix Functions

$$\frac{d^2 y}{dt^2} + Ay = 0, \quad y(0) = y_0, \quad y'(0) = y'_0$$

has solution

$$y(t) = \cos(\sqrt{A}t)y_0 + (\sqrt{A})^{-1} \sin(\sqrt{A}t)y'_0.$$

Toolbox of Matrix Functions

$$\frac{d^2 y}{dt^2} + Ay = 0, \quad y(0) = y_0, \quad y'(0) = y'_0$$

has solution

$$y(t) = \cos(\sqrt{A}t)y_0 + (\sqrt{A})^{-1} \sin(\sqrt{A}t)y'_0.$$

But

$$\begin{bmatrix} y' \\ y \end{bmatrix} = \exp \left(\begin{bmatrix} 0 & -tA \\ tI_n & 0 \end{bmatrix} \right) \begin{bmatrix} y'_0 \\ y_0 \end{bmatrix}.$$

Toolbox of Matrix Functions

$$\frac{d^2 y}{dt^2} + Ay = 0, \quad y(0) = y_0, \quad y'(0) = y'_0$$

has solution

$$y(t) = \cos(\sqrt{A}t)y_0 + (\sqrt{A})^{-1} \sin(\sqrt{A}t)y'_0.$$

But

$$\begin{bmatrix} y' \\ y \end{bmatrix} = \exp \left(\begin{bmatrix} 0 & -tA \\ tI_n & 0 \end{bmatrix} \right) \begin{bmatrix} y'_0 \\ y_0 \end{bmatrix}.$$

- In software want to be able evaluate interesting f at matrix args as well as scalar args.
- MATLAB has **expm**, **logm**, **sqrtm**, **funm**.

Application: Control Theory

Convert **continuous-time system**

$$\begin{aligned}\frac{dx}{dt} &= Fx(t) + Gu(t), \\ y &= Hx(t) + Ju(t),\end{aligned}$$

to **discrete-time state-space system**

$$\begin{aligned}x_{k+1} &= Ax_k + Bu_k, \\ y_k &= Hx_k + Ju_k.\end{aligned}$$

Have

$$A = e^{F\tau}, \quad B = \left(\int_0^{\tau} e^{Ft} dt \right) G,$$

where τ is the sampling period.

MATLAB Control System Toolbox: **c2d** and **d2c**.

The Average Eye

First order character of optical system characterized by **transference matrix**

$$T = \begin{bmatrix} S & \delta \\ 0 & 1 \end{bmatrix} \in \mathbb{R}^{5 \times 5},$$

where $S \in \mathbb{R}^{4 \times 4}$ is **symplectic**:

$$S^T J S = J = \begin{bmatrix} 0 & I_2 \\ -I_2 & 0 \end{bmatrix}.$$

Average $m^{-1} \sum_{i=1}^m T_i$ is not a transference matrix.

Harris (2005) proposes the average $\exp(m^{-1} \sum_{i=1}^m \log(T_i))$.

Markov Models

- Time-homogeneous continuous-time Markov process with transition probability matrix $P(t) \in \mathbb{R}^{n \times n}$.
- **Transition intensity matrix** Q : $q_{ij} \geq 0$ ($i \neq j$),
 $\sum_{j=1}^n q_{ij} = 0$, $P(t) = e^{Qt}$.

For *discrete-time* Markov processes:

Embeddability problem

When does a given **stochastic** P have a real logarithm Q that is an **intensity matrix**?

Markov Models (1)—Example

With $x = -e^{-2\sqrt{3}\pi} \approx -1.9 \times 10^{-5}$,

$$P = \frac{1}{3} \begin{bmatrix} 1 + 2x & 1 - x & 1 - x \\ 1 - x & 1 + 2x & 1 - x \\ 1 - x & 1 - x & 1 + 2x \end{bmatrix}.$$

- P diagonalizable, $\Lambda(P) = \{1, x, x\}$.
- Every primary log complex (can't have complex conjugate ei'vals).
- Yet a generator is the non-primary log

$$Q = 2\sqrt{3}\pi \begin{bmatrix} -2/3 & 1/2 & 1/6 \\ 1/6 & -2/3 & 1/2 \\ 1/2 & 1/6 & -2/3 \end{bmatrix}.$$

Markov Models (2)

- Suppose $P \equiv P(1)$ has a generator $Q = \log P$. Then $P(t)$ at other times is $P(t) = \exp(Qt)$. E.g., if P transition matrix for 1 year,
 $P(1/12) = e^{\frac{1}{12} \log P} \equiv P^{1/12}$ is matrix for 1 month.
- **Problem:** $\log P$, $P^{1/k}$ may have wrong sign patterns \Rightarrow “regularize”.

HIV to Aids Transition

- Estimated 6-month transition matrix.
- Four AIDS-free states and 1 AIDS state.
- 2077 observations (Charitos et al., 2008).

$$P = \begin{bmatrix} 0.8149 & 0.0738 & 0.0586 & 0.0407 & 0.0120 \\ 0.5622 & 0.1752 & 0.1314 & 0.1169 & 0.0143 \\ 0.3606 & 0.1860 & 0.1521 & 0.2198 & 0.0815 \\ 0.1676 & 0.0636 & 0.1444 & 0.4652 & 0.1592 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}.$$

Want to estimate the **1-month transition matrix**.

$$\Lambda(P) = \{1, 0.9644, 0.4980, 0.1493, -0.0043\}.$$

N. J. Higham and L. Lin.
On p th roots of stochastic matrices, LAA, 2011.

Outline

- 1 Definition and Properties
- 2 Applications
- 3 Theory**
- 4 Computing the Matrix Logarithm and its Fréchet derivative

Logs of $A = I_3$

$$B = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix},$$

$$C = \begin{bmatrix} 0 & 2\pi - 1 & 1 \\ -2\pi & 0 & 0 \\ -2\pi & 0 & 0 \end{bmatrix}, \quad D = \begin{bmatrix} 0 & 2\pi & 1 \\ -2\pi & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix},$$

$$e^B = e^C = e^D = I_3.$$

$$\Lambda(C) = \Lambda(D) = \{0, 2\pi i, -2\pi i\}.$$

All Solutions of $e^X = A$

Theorem (Gantmacher, 1959)

$A \in \mathbb{C}^{n \times n}$ nonsing with Jordan canonical form

$Z^{-1}AZ = J = \text{diag}(J_1, J_2, \dots, J_p)$. All solutions to $e^X = A$ are given by

$$X = Z U \text{diag}(L_1^{(j_1)}, L_2^{(j_2)}, \dots, L_p^{(j_p)}) U^{-1} Z^{-1},$$

where

$$L_k^{(j_k)} = \log(J_k(\lambda_k)) + 2j_k \pi i I_{m_k},$$

$j_k \in \mathbb{Z}$ arbitrary, and U an arbitrary nonsing matrix that commutes with J .

All Solutions of $e^X = A$: Classified

Theorem

$A \in \mathbb{C}^{n \times n}$ nonsing: p Jordan blocks, s distinct ei'vals.
 $e^X = A$ has a countable infinity of solutions that are **primary functions** of A :

$$X_j = Z \text{diag}(L_1^{(j_1)}, L_2^{(j_2)}, \dots, L_p^{(j_p)}) Z^{-1},$$

where $\lambda_i = \lambda_k$ implies $j_i = j_k$. If $s < p$ then $e^X = A$ has **non-primary solutions**

$$X_j(U) = Z U \text{diag}(L_1^{(j_1)}, L_2^{(j_2)}, \dots, L_p^{(j_p)}) U^{-1} Z^{-1},$$

where $j_k \in \mathbb{Z}$ arbitrary, U arbitrary nonsing with $UJ = JU$,
 and for each $j \exists i$ and k s.t. $\lambda_i = \lambda_k$ while $j_i \neq j_k$.

Logs of $A = I_3$ (again)

$$C = \begin{bmatrix} 0 & 2\pi - 1 & 1 \\ -2\pi & 0 & 0 \\ -2\pi & 0 & 0 \end{bmatrix}, \quad D = \begin{bmatrix} 0 & 2\pi & 1 \\ -2\pi & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix},$$

$$e^0 = e^C = e^D = I_3. \quad \Lambda(C) = \Lambda(D) = \{0, 2\pi i, -2\pi i\}.$$

$$U = \begin{bmatrix} 1 & \alpha & 0 \\ 0 & 1 & \alpha \\ 0 & 0 & 1 \end{bmatrix}, \quad \alpha \in \mathbb{C},$$

$$X = U \operatorname{diag}(2\pi i, -2\pi i, 0) U^{-1} = 2\pi i \begin{bmatrix} 1 & -2\alpha & 2\alpha^2 \\ 0 & 1 & -\alpha \\ 0 & 0 & 1 \end{bmatrix}.$$

Square Roots of Rotations

$$G(\theta) = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}.$$

$G(\theta/2)$ is the natural square root of $G(\theta)$.

For $\theta = \pi$,

$$G(\pi) = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}, \quad G(\pi/2) = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}.$$

$G(\pi/2)$ is a **nonprimary** square root.

Principal Logarithm and p th Root

Let $A \in \mathbb{C}^{n \times n}$ have no eigenvalues on \mathbb{R}^- .

Principal log

$X = \log(A)$ denotes unique X such that

- $e^X = A$.
- $-\pi < \text{Im}(\lambda(X)) < \pi$.

Principal Logarithm and p th Root

Let $A \in \mathbb{C}^{n \times n}$ have no eigenvalues on \mathbb{R}^- .

Principal log

$X = \log(A)$ denotes unique X such that

- $e^X = A$.
- $-\pi < \text{Im}(\lambda(X)) < \pi$.

Principal p th root

For integer $p > 0$, $X = A^{1/p}$ is unique X such that

- $X^p = A$.
- $-\pi/p < \arg(\lambda(X)) < \pi/p$.

Outline

- 1 Definition and Properties
- 2 Applications
- 3 Theory
- 4 **Computing the Matrix Logarithm and its Fréchet derivative**

Henry Briggs (1561–1630)

- **Arithmetica Logarithmica** (1624)
- Logarithms to base 10 of 1–20,000 and 90,000–100,000 to **14 decimal places**.

Henry Briggs (1561–1630)

- **Arithmetica Logarithmica** (1624)
- Logarithms to base 10 of 1–20,000 and 90,000–100,000 to **14 decimal places**.

Briggs must be viewed as one of the great figures in numerical analysis.

**—Herman H. Goldstine,
*A History of Numerical Analysis (1977)***

ARITHMETICA

LOGARITHMICA

SIVE

LOGARITHMORVM CHILIADES TRIGINTA, PRO

numeris naturali serie crescentibus ab unitate ad
20,000 : et a 90,000 ad 100,000. Quorum ope multa
perficiuntur Arithmetica problemata
et Geometrica.

HOS NUMEROS PRIMVS
INVENIT CLARISSIMVS VIR IOHANNES

NEPERVS Baro Merchistonij : eos autem ex eiusdem sententia
mutavit, eorumque ortum et usum illustravit HENRICVS BRIGGIUS,
in celeberrima Academia Oxoniensi Geometrix
professor SAVILIANVS.

DEVS NOBIS VSVRAM VITÆ DEDIT
ET INGENII, TANQVAM PECVNIAE,
NULLA PRÆSTITVTA DIE.



LONDINI
Excudebat GVLIELMVS
IONES. 1624.

Numeri continue Medij inter Denarium & Vnicatem.

Logarithmi Rationales.

10	1,000
1	31622,77660,16837,93319,98893,54
2	17782,79410,05822,28011,97304,13
3	13335,21432,16332,40256,65389,308
4	11547,81984,68945,81796,61918,213
5	10746,07828,32131,74972,13817,6538
6	10366,32928,43769,79972,90627,3131
7	10181,51721,71818,18414,73723,8144
8	10090,35044,84144,74377,59005,1391
9	10045,07364,42546,25156,64670,6113
10	10022,51148,29291,29154,65611,7367
11	10011,24941,39987,98757,85395,52805
12	10005,62312,60220,86366,18495,91839
13	10002,81116,78778,01323,99249,64325
14	10001,40548,51694,72581,62767,32715
15	10000,70217,12941,14335,38811,70845
16	10000,35135,27746,18565,08581,37077
17	10000,17567,48442,26738,33846,78274
18	10000,08783,70363,46121,46574,07431
19	10000,04391,84217,31672,36281,88083
20	10000,02195,91867,55542,03317,07719
21	10000,01097,95873,50204,09754,72940
22	10000,00548,99291,68211,14626,60250,4
23	10000,00274,48977,07328,95091,25449,9
24	10000,00137,24477,59510,83282,69572,5
25	10000,00068,62238,56210,25737,18748,2
26	10000,00034,31119,22218,83912,75020,8
27	10000,00017,15559,59637,84719,93879,1
28	10000,00008,57779,79451,03051,17588,8
29	10000,00004,28889,86633,54198,42901,3
30	10000,00002,14444,94793,77767,42970,4
31	10000,00001,07222,47391,14050,76926,8
32	10000,00000,53611,23594,13317,14831,4
33	10000,00000,26505,61846,70731,51508,7
34	10000,00000,13402,80923,26383,99277,7
35	10000,00000,06701,40461,60946,55519,6
36	10000,00000,03350,70230,99911,91730,0
37	10000,00000,01675,35115,39815,61857,6
38	10000,00000,00837,67557,69872,72426,9
39	10000,00000,00418,83778,84927,59087,9
40	10000,00000,00209,41889,42461,60262,5
41	10000,00000,00104,70944,71230,25311,0
1	0,500
2	0,25
3	0,125
4	0,0625
5	0,03125
6	0,015625
7	0,0078125
8	0,00390625
9	0,001953125
10	0,0009765625
11	0,00048828125
12	0,000244140625
13	0,0001220703125
14	0,00006103515625
15	0,000030517578125
16	0,0000152587890625
17	0,00000762939453125
18	0,000003814697265625
19	0,0000019073486328125
20	0,00000095367431640625
21	0,000000476837158203125
22	0,0000002384185791015625
23	0,00000011920928955078125
24	0,000000059604644773390625
25	0,0000000298023223876953125
26	0,00000001490116119384765625
27	0,000000007450580596923828125
28	0,0000000037252902984619140625
29	0,00000000186264514923095703125
30	0,000000000931322574615478515625
31	0,000000000465612873077392578125
32	0,0000000002328306365386962890625
33	0,000000000116415321826934814453125
34	0,0000000000582076609134674072265625
35	0,00000000002910383045673370361328125
36	0,000000000014551915228366851806640625
37	0,0000000000072759576141834259033203125
38	0,00000000000363799880709171295166015625
39	0,000000000001818998403545856475830078125
40	0,0000000000009094947017729282379150390625
41	0,00000000000045474715088646411807710112

Briggs' Log Method (1617)

$$\log(ab) = \log a + \log b \quad \Rightarrow \quad \log a = 2 \log a^{1/2}.$$

Use repeatedly:

$$\log a = 2^k \log a^{1/2^k}.$$

Write $a^{1/2^k} = 1 + x$ and note $\log(1 + x) \approx x$. Briggs worked to base 10 and used

$$\log_{10} a \approx 2^k \cdot \log_{10} e \cdot (a^{1/2^k} - 1).$$

When Does $\log(BC) = \log(B) + \log(C)$?

Theorem

Let $B, C \in \mathbb{C}^{n \times n}$ commute and have no ei'vals on \mathbb{R}^- . If for every ei'val λ_j of B and the corr. ei'val μ_j of C , $|\arg \lambda_j + \arg \mu_j| < \pi$, then $\log(BC) = \log(B) + \log(C)$.

When Does $\log(BC) = \log(B) + \log(C)$?

Theorem

Let $B, C \in \mathbb{C}^{n \times n}$ commute and have no ei'vals on \mathbb{R}^- . If for every ei'val λ_j of B and the corr. ei'val μ_j of C , $|\arg \lambda_j + \arg \mu_j| < \pi$, then $\log(BC) = \log(B) + \log(C)$.

Proof. $\log(B)$ and $\log(C)$ commute, since B and C do. Therefore

$$e^{\log(B)+\log(C)} = e^{\log(B)} e^{\log(C)} = BC.$$

Thus $\log(B) + \log(C)$ is *some* logarithm of BC . Then

$$\operatorname{Im}(\log \lambda_j + \log \mu_j) = \arg \lambda_j + \arg \mu_j \in (-\pi, \pi),$$

so $\log(B) + \log(C)$ is the *principal* logarithm of BC . \square

Inverse Scaling and Squaring Method

Take $B = C$ in previous theorem:

$$\log A = \log(A^{1/2} \cdot A^{1/2}) = 2 \log(A^{1/2}),$$

since $\arg \lambda(A^{1/2}) \in (-\pi/2, \pi/2)$.

Inverse Scaling and Squaring Method

Take $B = C$ in previous theorem:

$$\log A = \log(A^{1/2} \cdot A^{1/2}) = 2 \log(A^{1/2}),$$

since $\arg \lambda(A^{1/2}) \in (-\pi/2, \pi/2)$.

Use Briggs' idea: $\log A = 2^k \log(A^{1/2^k})$.

Inverse Scaling and Squaring Method

Take $B = C$ in previous theorem:

$$\log A = \log(A^{1/2} \cdot A^{1/2}) = 2 \log(A^{1/2}),$$

since $\arg \lambda(A^{1/2}) \in (-\pi/2, \pi/2)$.

Use Briggs' idea: $\log A = 2^k \log(A^{1/2^k})$.

Kenney & Laub's (1989) **inverse scaling and squaring** method:

- Bring A close to I by repeated square roots.
- Approximate $\log(A^{1/2^s})$ using an $[m/m]$ Padé approximant $r_m(x) \approx \log(1 + x)$.
- Rescale to find $\log(A)$.

Choice of Parameters s, m

Must have $\|I - A^{1/2^s}\| < 1$.

- Larger Padé degree m means smaller s .

Let $h_{2m+1}(X) = e^{r_m(X)} - X - I$.

Assume $\rho(r_m(X)) < \pi$, so $\log(e^{r_m(X)}) = r_m(X)$. Then

$$r_m(X) = \log(I + X + h_{2m+1}(X)) =: \log(I + X + \Delta X),$$

where

$$h_{2m+1}(X) = \sum_{k=2m+1}^{\infty} c_k X^k.$$

Bounding the Backward Error

Want to bound norm of $h_{2m+1}(X) = \sum_{k=2m+1}^{\infty} c_k X^k$.

- Non-normality implies $\rho(A) \ll \|A\|$.

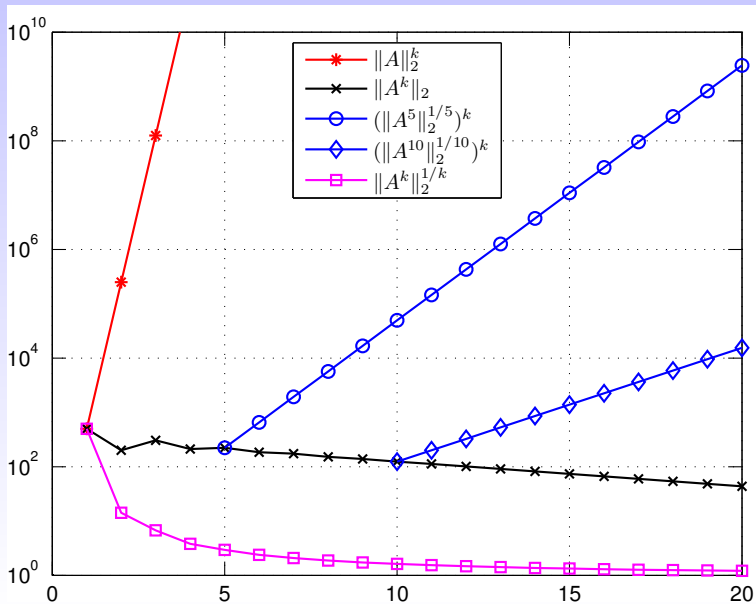
- Note that

$$\rho(A) \leq \|A^k\|^{1/k} \leq \|A\|, \quad k = 1 : \infty.$$

and $\lim_{k \rightarrow \infty} \|A^k\|^{1/k} = \rho(A)$.

- Use $\|A^k\|^{1/k}$ instead of $\|A\|$ in the truncation bounds.

$$A = \begin{bmatrix} 0.9 & 500 \\ 0 & -0.5 \end{bmatrix}.$$



Algorithm of **Al-Mohy & H (2011)**

- Truncation bounds use $\|A^k\|^{1/k}$ rather than $\|A\|$, leading to major benefits in speed and accuracy.
Matrix norms not such a blunt tool!
- Use *estimates* of $\|A^k\|$ (alg of H & Tisseur (2000)).
- Choose s and m to achieve double precision backward error at minimal cost.
- Initial Schur decomposition: $A = QTQ^*$.
- Directly and accurately compute certain elements of $T^{1/2^s} - I$ and $\log(T)$. Use

$$a^{1/2^s} - 1 = \frac{a - 1}{\prod_{i=1}^s (1 + a^{1/2^i})}.$$

Fréchet Derivative of Logarithm

$$f(A + E) - f(A) - L(A, E) = o(\|E\|).$$

- Integral formula

$$L(A, E) = \int_0^1 (t(A - I) + I)^{-1} E (t(A - I) + I)^{-1} dt.$$

- Method based on

$$f \left(\begin{bmatrix} X & E \\ 0 & X \end{bmatrix} \right) = \begin{bmatrix} f(X) & L(X, E) \\ 0 & f(X) \end{bmatrix}.$$

- Kenney & Laub (1998): Kronecker–Sylvester alg, Padé of $\tanh(x)/x$. Requires complex arithmetic.

Algorithm of **Al-Mohy, H & Relton (2012)**

Fréchet differentiate the ISS algorithm!

- 1 $E_0 = E$
- 2 for $i = 1:s$
- 3 Compute $A^{1/2^i}$.
- 4 Solve the Sylvester eqn $A^{1/2^i} E_i + E_i A^{1/2^i} = E_{i-1}$.
- 5 end
- 6 $\log(A) \approx 2^s r_m(A^{1/2^s} - I)$
- 7 $L_{\log}(A, E) \approx 2^s L_{r_m}(A^{1/2^s} - I, E_s)$

Backward Error Result

$$r_m(X) = \log(I + X + \Delta X),$$



$$L_{r_m}(X, E) = L_{\log}(I + X + \Delta X, E + \Delta E).$$

Conclusions & Future Directions


- Log appears in a growing number of applications.
 - Have good algorithms for $\log(A)$, $L_{\log}(A)$ and estimating the condition number.
 - If A is real can work entirely in real arithmetic.
-
- Conditioning of $f(A)$.
 - Non-primary functions.
 - Functions of structured matrices.



References I

-  A. H. Al-Mohy and N. J. Higham.
A new scaling and squaring algorithm for the matrix exponential.
SIAM J. Matrix Anal. Appl., 31(3):970–989, 2009.
-  A. H. Al-Mohy and N. J. Higham.
Improved inverse scaling and squaring algorithms for the matrix logarithm.
MIMS EPrint 2011.83, Manchester Institute for Mathematical Sciences, The University of Manchester, UK, Oct. 2011.
18 pp.
Revised April 2012. To appear in *SIAM J. Sci. Comput.*

References II


 T. Charitos, P. R. de Waal, and L. C. van der Gaag.
Computing short-interval transition matrices of a
discrete-time Markov chain from partially observed
data.

Statistics in Medicine, 27:905–921, 2008.

 W. F. Harris.

The average eye.

Ophthal. Physiol. Opt., 24:580–585, 2005.




 N. J. Higham.

The Matrix Function Toolbox.




[http:](http://www.ma.man.ac.uk/~higham/mftoolbox)

[//www.ma.man.ac.uk/~higham/mftoolbox.](http://www.ma.man.ac.uk/~higham/mftoolbox)

References III

-  N. J. Higham.
Evaluating Padé approximants of the matrix logarithm.
SIAM J. Matrix Anal. Appl., 22(4):1126–1135, 2001.
-  N. J. Higham.
Functions of Matrices: Theory and Computation.
Society for Industrial and Applied Mathematics,
Philadelphia, PA, USA, 2008.
ISBN 978-0-898716-46-7.
xx+425 pp.
-  N. J. Higham and A. H. Al-Mohy.
Computing matrix functions.
Acta Numerica, 19:159–208, 2010.

References IV

-  N. J. Higham and L. Lin.
On p th roots of stochastic matrices.
Linear Algebra Appl., 435(3):448–463, 2011.
-  C. S. Kenney and A. J. Laub.
Condition estimates for matrix functions.
SIAM J. Matrix Anal. Appl., 10(2):191–209, 1989.
-  C. S. Kenney and A. J. Laub.
A Schur–Fréchet algorithm for computing the logarithm
and exponential of a matrix.
SIAM J. Matrix Anal. Appl., 19(3):640–663, 1998.